Do ice caves exist on Mars?

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A B S T R A C T

We have developed a numerical model for assessing the lifetime of ice deposits in martian caves that are open to the atmosphere. Our model results and sensitivity tests indicate that cave ice would be stable over significant portions of the surface of Mars. Ice caves on Earth commonly occur in lava tubes, and Mars has been significantly resurfaced by volcanic activity during its history, including the two main volcanic provinces, the Tharsis and Elysium rises. These areas, known or suspected of having subsurface caves and related voids are among the most favorable regions for the occurrence of ice stability. The martian ice cave model predicts regions where, if caves occur, would potentially be areas of astrobiological importance as well as possible water sources for future human missions to Mars.

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1. Introduction and background

Terrestrial caves are ubiquitous and occur in every major type of rock (Boston et al., 2004). They can provide sources of shelter and water, and as such are important biological habitats. On Mars, caves may be especially important forms of shelter, given the harsh radiation environments at the surface (Boston et al., 1992, 2004; Leveille and Datta, 2010; Schulze-Makuch et al., 2005). In addition, low-latitude martian caves may be viable water sources (Boston et al., 2004). While caves are often defined as natural cavities in the regolith large enough to admit human entry, the term in this paper is more broadly defined as any air-filled natural cavity beneath the planetary surface that has a connection with the atmosphere.

Aside from several researchers suggesting that caves exist on Mars (Boston, 2004b; Carr et al., 1977; Wynne et al., 2008), there is now some direct evidence of martian caves as well (Cushing et al., 2007a,b). Frederick et al. (2000) and Leveille and Datta (2010) hypothesized that martian lava tubes may harbor ice. Most of the martian caves hypothesized have been related to lava processes. It is possible, however, that other subterranean cavities may exist on Mars. Some cave formation mechanisms that may occur on Mars include mass wasting (e.g. undercutting of scarps) and tectonic processes leading to subsurface cracking (Boston, 2004b). Another interesting potential source of caves on Mars may be related to dissolution of soluble rock, presumably occurring during an earlier era when Mars was hypothesized to have been much wetter (Boston, 2004b). On Earth, such solution caves occur often in limestones and evaporites, but also in quartzites, granites and sandstones (Boston, 2004b). Hence it is possible that a variety of formation mechanisms on Mars may have created air-filled caves. The term “ice cave” is generally different than “glacier cave”; the latter term is generally reserved for caves within ice (Yonge, 2004). The term “ice cave” has been defined in Yonge (2004) as a cave with both seasonal and perennial ice deposits. Ice caves are, for the purposes of this study, broadly defined as caves containing perennial ice, and hence the term applies to caves containing ice deposits where typical annual net ice loss rates are low.

The ice source for ice caves include wind-blown snow, frozen ponded rainwater, atmospherically deposited frost (Hoarfrost) or some combination of these sources. For Earth, such water sources are commonplace. At first glance, present-day Mars appears devoid of such water sources at low-latitudes. Previous climates of Mars, however, have been hypothesized to be much wetter than present-day Mars (Mischna et al., 2003, among others). We discuss the presence of water ice on present-day Mars in greater detail later in this paper. In permafrost regions of Earth the freezing of moist sediments, characterized by intra-particle aggregations (lenses, needles, etc.) between soil grains, can potentially be another type of ice in caves (Yonge, 2004). We have limited our modeled ice to be relatively pure, with only very small amounts of dust mixed in (if any), and no dust layer on top of the ice.

Ice caves do not necessarily require that the external ambient air temperature be subfreezing for much of the year; instead many terrestrial ice caves exist at low-latitudes, and are able to contain ice year-round due to a favorable air circulation pattern between the cave and the outside air (Racovita and Onac, 2000). If the cave...
geometry favors the preferential accumulation of cold air, while expelling much of the warm air, then the cave will function as a "cold trap". Examples of such cold trap caves containing ice include pits or vertical shafts, though more complex geometries exist as well (Racovita and Onac, 2000; Yonge, 2004). Lava tubes often lack extensive fissures, and are therefore more likely to have limited air circulation of the type favoring the cold-trapping behavior (Yonge, 2004). Hence lava tubes serve well the requirements for the geometry that is being modeled in this paper. The cold-trapping behavior of a particular terrestrial ice cave, in this case a limestone cave, is shown in Fig. 1.

2. Model description

The cave modeled in our study is a subterranean room (square floor, dimensions 10 m × 10 m) with a ceiling height of 8 m. There is a small opening ("chimney") in the ceiling permitting air exchange with the outside (Fig. 2). The chimney is located near the edge of the ceiling.

The cave wall temperature was computed via the standard 1-D heat conduction equation:

$$\frac{\partial T}{\partial t} = k \frac{\partial^2 T}{\partial x^2}$$

Here $T$ is temperature, $t$ is time, $x$ is distance and $k$ is the thermal diffusivity $\frac{k^0}{\rho C_p}$, where $k^0$ is the thermal conductivity, $\rho$ is the wall material density and $C_p$ the specific heat capacity of the wall material.

The thermal conductivity of the walls was derived for each surface gridbox from the Ames thermal inertia map for Mars (which is currently used in the Ames Mars General Circulation Model) by using the following relation (which is an empirical fit to data from Figs. 3 and 4 of Moore et al. (1989)):

$$\rho = 11.187 \left( \frac{TI}{41.840} \right)^{0.3895}$$

where $\rho$ is the ground density in kg/m$^3$ and $TI$ is the thermal inertia of the location, in standard Thermal Inertia Units (TIU; 1 TIU = $\frac{J m^2 K}{W s}$). A fixed value of specific heat capacity was then used in order to then infer the thermal conductivity using the relation

$$k^0 = \frac{TI^2}{\rho C_p}$$

This method of deriving the thermal conductivity based solely on thermal inertia is admittedly crude, so we also modeled two additional scenarios where both the ground and cave walls were composed of high thermal inertia (rock) and low thermal inertia (dust) material (explained below).

The cave ceiling thickness was assumed to be equal to or thicker than several seasonal skin depths; the thermal skin depth is given by:

$$d = \sqrt{\frac{k^0 \tau}{\pi \rho C_p}}$$
Here $d$ is the depth, $k'$ is the thermal conductivity and $t$ is the period of the thermal cycle. The ceiling thickness of several skin depths was chosen in order to permit the same temperatures found in the cave walls to be applicable to the ceiling and bottom as well. Depending on the thermal inertia of the surface material (which was chosen in order to permit the same temperatures found in the cave walls to be applicable to the ceiling and bottom as well). The ceiling thickness of several skin depths of the thermal cycle. The ceiling thickness of several skin depths may be considered to be in the center of the cave floor.

The ice deposit in the cave is assumed to be a 1 m$^2$ plate composed of solid ice with a thickness of 3 cm. It is assumed that the position of the ice is such that no portion of the outside sky is visible through the chimney. For purposes of this study, the ice plate may be considered to be in the center of the cave floor.

The ice is modeled as a single layer, and a mass and energy conserving finite-volume approach is used to compute the mass and energy balance. The energy and mass balance in the ice sheet is computed via:

$$\frac{\partial U}{\partial t} = -k \frac{\partial T}{\partial z}_{\text{ice bottom}} - k \frac{\partial T}{\partial z}_{\text{ice surface}} - \sigma^4 + S_H + F_{ir} - L \frac{\partial M}{\partial t} \quad (5)$$

where $U$ is the (area normalized) energy of the ice layer, $t$ is time, $-k \frac{\partial T}{\partial z}$ is the heat flux conduction term from the bottom of the ice plate or the ice plate surface, $-\sigma^4$ is the outgoing IR flux by the ice plate, $S_H$ is the sensible heat flux, $F_{ir}$ is the IR flux radiated by the cave walls and ceiling and $L \frac{\partial M}{\partial t}$ is the latent heat due to mass gain or loss. These terms are explained in the sections below. No atmospheric heating (IR) term between the cave air and the ice plate was included because of the small air mass in the cave.

In order to compute both the latent heat and sensible heat terms, we begin by noting that the sensible heat “drag” coefficient $C_{dh}$ and momentum drag coefficient $C_{dm}$ may be defined (Savijarvi, 1995; Haberle et al., 1999):

$$C_{dm} = F_m \left( \frac{k}{ln(z/Z_0)} \right)^2 \quad (6)$$

$$C_{dh} = (F_h)^{1.2} \left( \frac{k}{ln(z/Z_0)} \right) \quad (7)$$

Here $k$ is the Von Karman constant (commonly taken to be 0.4). The stability functions are defined by (Hourdin et al., 1995; Haberle et al., 1999):

$$F_m = \left( 1 - 64 R_l^{1/2} \right) R_l < 0$$

$$F_h = \left( \frac{1}{1 + 15 \sqrt{z/H}} \right) R_l > 0$$

Which are defined with the Richardson number $R_l = \frac{g H}{\nu u^*}$ where $g$ is gravity, $z$ is the instrument height, $u$ is the wind speed, $\lambda = T_a - T_i$ and $T = \frac{T_a + T_i}{2}$ as suggested by Sutton et al. (1978) and $T_a$ and $T_i$ are the temperatures in the air and at the surface respectively.

The friction velocity $u^*$ is then (Haberle et al., 1999):

$$u^* = \left( C_{dm} \right)^{1/2} u \quad (8)$$

The sensible heating and latent heat terms were found by summing the free and forced loss terms. Using Eqs. (6)–(8), the forced sensible heat term is given by (Haberle et al., 1999):

$$H_{forced} = -\rho_{air} C_{ps} u^* C_{dm} (T_a - T_i) \quad (9)$$

where $\rho_{air}$ is the density of the air and $C_{ps}$ is the specific heat capacity of the air.

The free sensible heat loss term is (Holman, 2002):

$$H_{free} = 0.15(T_a - T_i) k_{gas} (Gr Pr)^{3/4} \quad (10)$$

where $Gr$ and $Pr$ are the Grashof and Prandtl numbers, respectively and $k_{gas}$ is the thermal conductivity for CO$_2$ gas (Holman, 2002).

The latent heat term is determined by computing the ice sublimation/deposition terms. The ice sublimation term was computed by adding the free and forced convective mass loss terms together. There is some experimental evidence that such an approach is correct (Chittenden et al., 2008), at least for wind speeds of less than or equal to 10 m/s. The GCM surface wind speeds can often be $\sim 10$ m/s, however as mentioned previously the ice plate in the cave was exposed to a considerably lower wind speed than the surface winds, due to the cave geometry studied affecting the cave wind circulation pattern.

The forced mass-loss term was computed by using Eqs. (6)–(8) as:

$$m_{forced} = u^* C_{dm} \rho_{air} (w - w_{sat}) \quad (11)$$

where $w$ and $w_{sat}$ are the mass mixing ratios of water in the air and at the ice surface, respectively.

The free convective mass-loss term is given by (Ingersoll, 1970; Hecht, 2002 and others):

$$m_{free} = 0.17(e - e_{sat}) M_w \frac{D}{R} \left( \frac{\Delta \rho_{air}}{\rho_{air}} \right) \left( \frac{g}{\nu} \right)^{1/3} \quad (12)$$

where $\Delta \rho_{air} / \rho_{air} = \frac{26 \Delta e_{sat}}{(44p - 26 \Delta e_{sat})}$ and $v$ is the kinematic viscosity of CO$_2$ gas, $e_{sat}$ the water saturation vapor pressure, $R$ the gas constant and $D = 32f^{1/2}/p$ is the diffusion coefficient of H$_2$O vapor in CO$_2$ gas.

The $F_{ir}$ term is the infrared radiation emitted by the surrounding surfaces and absorbed by the ice plate, and is computed by assuming that the walls emit as a blackbody:

$$F_{ir} = \sigma T^4 \quad (13)$$

The emissivity of the walls are an unknown, so we used a value of 0.928, taken by averaging several values in Mira et al. (2007) corresponding to a mixture of 99% sand and 1% silt. Model sensitivity tests were conducted on the wall emissivity and are summarized in Table 1.

CO$_2$ ice condensation has been omitted in this study. At Mars pressures, which vary with altitude and season, the condensation of CO$_2$ should occur in the range of 142–149 K. At such low temperatures the atmosphere is able to hold only very small amounts of water. Further, the addition of a CO$_2$ ice cap on top of the water ice plate would probably inhibit water ice loss (and thereby lengthen ice lifetimes). Hence we view our age of ice estimates to be conservative. It is possible, with the addition of CO$_2$ ice condensation, that the water ice lifetimes are longer.

In order to estimate the mean horizontal wind speed over the ice plate, it was necessary to estimate cave airflow. The airflow for the basic cave configuration was simulated using a Lattice-Boltzmann Model with a modification for turbulence (see Appendix A) for a low-velocity CO$_2$ atmosphere. As can be seen in Fig. 2, the general geometry is that of a shear-driven cavity, but with a chimney restriction. Our airflow calculations show that, depending on the exact cave configuration, after approximately 9 min (our integration time interval) the average horizontal airspeed over the floor ice plate was usually between 0.1% and 10% of the surface wind speed. We therefore assume the horizontal airspeed over the ice plate to be 1% of the GCM-provided surface wind speed (as a wind “scaling factor” of 0.01). However, due to the strong dependence of the floor wind scaling factor on the particular cave geometry (including cave ceiling thickness, room dimensions, chimney geometry, chimney location in the cave ceiling and ice
plate location), we have varied the wind scaling factor by a large value (up to 10× and 1/10×) in our sensitivity tests. The airflow analysis is shown in Fig. 3.

In a manner similar to Eq. (5), the energy balance in the cave air is given by:

$$\frac{\partial U}{\partial t} = k \frac{\partial T}{\partial z}_{\text{cave walls}} + k \frac{\partial T}{\partial z}_{\text{ice surface}} - S_H + L \frac{\partial M}{\partial t} \middle|_{\text{ice}}$$

$$+ L \frac{\partial M}{\partial t} \middle|_{\text{cave walls}} \left( S_{\text{cave}} - S_{\text{plate}} \right)$$

$$+ \left[ k \frac{\partial T}{\partial z}_{\text{ice surface}} - S_H + L \frac{\partial M}{\partial t} \right] S_{\text{plate}}$$

where the terms are defined in the same manner as Eq. (5), except that in this case $U$ is the total cave air energy and $S_{\text{cave}}$ is the surface area of the cave interior and $S_{\text{plate}}$ is the area of the initial ice plate on the cave floor. Note that for the cave air, the latent heat and heat conduction terms are computed between the air and all of the surfaces within the cave (either ice or bare soil). If the walls of the cave are covered in a thin layer of frost, then the latent heat and heat conduction terms are computed between the frost-covered walls and the cave air. In this case the IR emission terms were excluded because there was only a small air mass in the cave (typically ~11 kg for the entire cave) and in practice the cave walls (either icy or bare soil) were essentially the same temperature as the cave air.

We retain water vapor in the cave that has been lost from the surface of the ice (i.e. the relative-humidity of the cave is allowed to increase as a result of ice sublimation). Humidity changes as well when the cave is flushed with outside air. Note that high relative-humidity within the cave air serves to suppress ice mass loss, or to add mass to the ice via frost deposition. Accordingly the ice lifetimes may be longer if particular caves do not have a chimney ventilation system to be used for air exchanges.

In this study, growing ice is modeled as frost deposition. Frost deposition is an involved topic in itself, and has been studied extensively in engineering (Cheng and Cheng, 2001; Sherif et al., 1993, among others). Note that Eq. (11) is one of the equations used in our model for mass loss. It seems unlikely, however, that Eq. (11) would work well for mass (frost) deposition when the gradient is reversed. Hence in this paper we have adopted a different semi-empirical model for frost deposition (explained below). In our model the frost layer, which forms on top of the ice plate, is assumed to be of uniform thickness and growing in a direction perpendicular to the plate. The frost is also assumed to be of uniform density at a given instant, and to have constant convective heat and mass transfer coefficients. These assumptions are shared by other studies, including Cheng and Cheng (2001) and Sherif et al. (1993).

In our approach, the frost deposition for Mars is modeled by applying the work of Sherif et al. (1993), which was originally developed for terrestrial environments. Following Sherif et al. (1993), we begin by assuming that the energy transferred from the humid air stream can be written as being conducted through the frost or stored within the frost layer:

$$h_i (i_a - i_p) = k_f \frac{dT_f}{dz_f} + \psi$$

where $h_i$ is the enthalpy transfer coefficient, $i_a$ and $i_p$ are the enthalpies of moist air evaluated at air temperature and frost surface

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**Table 1**

Model sensitivity tests. These sensitivity tests were done for a single map location, centered at 0° Latitude by 0° Longitude. Base case ice loss rate for this location: $-2.89 \times 10^{-2}$ kg/yr.

<table>
<thead>
<tr>
<th>Parameter (range)</th>
<th>Ice loss rate low parameter value (kg/year)</th>
<th>Ice loss rate high parameter value (kg/year)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Frost density minimum (2.229 kg/m²; 0.1×, 10×)</td>
<td>$-2.89 \times 10^{-2}$</td>
<td>$-2.89 \times 10^{-2}$</td>
</tr>
<tr>
<td>Notes: Relates to minimum frost density used in frost deposition model. See text after Eq. (19)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Frost density total amount (0.5×, 1.5×)</td>
<td>$-2.89 \times 10^{-2}$</td>
<td>$-2.89 \times 10^{-2}$</td>
</tr>
<tr>
<td>Notes: Scaling for Eq. (9)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>GCM water mixing ratio (0.5×, 2×)</td>
<td>$-3.88 \times 10^{-2}$</td>
<td>$-1.81 \times 10^{-2}$</td>
</tr>
<tr>
<td>Outside air temperature (-10 K, +10 K)</td>
<td>$-3.94 \times 10^{-3}$</td>
<td>$-2.13 \times 10^{-1}$</td>
</tr>
<tr>
<td>Notes: Every GCM-supplied air temp.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Ground Thermal Inertia TIU (0.5×, 1.5×)</td>
<td>$-1.87 \times 10^{-2}$</td>
<td>$-4.07 \times 10^{-2}$</td>
</tr>
<tr>
<td>Notes: Ground T1 affects thermal conductivity. See thermal conductivity sensitivity maps</td>
<td></td>
<td></td>
</tr>
<tr>
<td>GCM ground sfc. temperature (-10 K, +10 K)</td>
<td>$-1.75 \times 10^{-2}$</td>
<td>$-4.32 \times 10^{-2}$</td>
</tr>
<tr>
<td>Z_instrument (instrument height in meters) (1.61: 1.2, 2.2)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Notes: For the Richardson number and Eq. (7)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Ice drag coeff. (0.002; 0.1×, 10×)</td>
<td>$-2.89 \times 10^{-2}$</td>
<td>$-2.89 \times 10^{-2}$</td>
</tr>
<tr>
<td>Windspeed (0.3×, 10×)</td>
<td>$-2.89 \times 10^{-2}$</td>
<td>$-2.89 \times 10^{-2}$</td>
</tr>
<tr>
<td>Wall emissivity (0.928 ± 0.05)</td>
<td>$-2.89 \times 10^{-2}$</td>
<td>$-2.89 \times 10^{-2}$</td>
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</tbody>
</table>
temperature, $k_f$ the thermal conductivity of frost, $S_f$ is frost thickness, $T_{fs}$ the frost surface temperature and $\psi$ the energy storage term. Similar to Sherif et al. (1993) we will hereafter neglect the storage term. The energy transfer rate $Q$ in the frost layer is governed by the sensible and latent heat exchanged with the humid airstream:

$$Q = |h(T_a - T_{fs}) - L_h(W_a - W_{fs})|A_{fc}$$

(16)

Where $L$ is the latent heat of sublimation of frost, $h$ and $h_o$ are the convective heat and mass transfer coefficients, $A_{fc}$ is the area of the frost surface, $W_a$ and $W_{fs}$ are the humidity ratios \((k_{vapour}/k_{dry} air)\) evaluated at the air temperature and frost surface temperature, $T_a$ and $T_{fs}$ are air temperature and surface temperature respectively.

The mass balance is given by

$$h_s(W_a - W_{fs}) = \frac{\partial (\rho_f S_f)}{\partial t} = S_f \frac{d\rho_f}{dt} + \rho_f \frac{dS_f}{dt}$$

(17)

where $\rho_f$ and $S_f$ is the density and thickness of the frost layer and $t$ is time.

In this model we assume, as others have done, that the forced convective heat transfer coefficient $\rho_f$ may be approximated over a flat horizontal plate as

$$h = 0.322 Pr^{1/3} Re^{1/2} \frac{k_{air}}{x}$$

(18)

Here $K$ is the thermal conductivity of the air and $x$ is the distance from the leading edge of the plate. The density of the frost has been found to depend on the temperatures of both the free airstream, the substrate temperature and the airstream humidity (Cheng and Cheng, 2001). In our model we use the empirical frost density function devised by Hayashi et al. (1977a,b) for Earth air. Hayashi et al. (1977a) devised a parameterization of the frost density $\rho_f$ based on the frost surface temperature $T_{fs}$:

$$\rho_f = 650 e^{0.227 (T_{fs})}$$

(19)

Here the density expression is reformulated for units of Celsius and kg/m$^3$. The Hayashi et al. parameterization is technically valid for an airstream temperature range of 248.15 $<$ $T_a$ $<$ 273.15 (K), airstream velocities between 2 and 6 m/s, and an airstream humidity ratio of 0.0079 $k_{vapour}/k_{dry} air$. We have adapted the above expression for Mars temperatures by specifying the initial frost density for temperature below $-$248 K to be the lowest parameterized value within the original range, namely 2.229 kg/m$^3$. To our knowledge, no similar frost densification studies have been done for water ice in a low-pressure CO$_2$ atmosphere, so it is unknown whether the above frost density parameterization is completely accurate for a Mars environment, especially at low temperatures ($\sim$150 K). We have, however, conducted model sensitivity tests of this lower density threshold value (2.229 kg/m$^3$), and found that the model was not sensitive to this minimum frost density, even varied by a factor of 10.

The above frost density expression is clearly unsuitable for a scenario where the frost surface melts and the meltwater refreezes at depth within the frost layer. However during our simulations for Mars caves the frost surface never reached the melting point.

Differentiating (19) with respect to time, substituting into (17) and expanding we get

$$h_s(W_a - W_{fs}) = \rho_f \frac{dS_f}{dt} \frac{dT_{fs}}{dt} + S_f \left(147.55 e^{0.227 (T_{fs})}\right) \frac{dT_{fs}}{dt}$$

(20)

Then substituting (15) into (20) one gets

$$\frac{dT}{dt} = \frac{h_s(W_a - W_{fs})}{\rho_f h_s(T_a - T_{fs}) + S_f \left(147.55 e^{0.227 (T_{fs})}\right)}$$

(21)

By a similar process we find the following expression for time-derivative of the frost thickness:

$$\frac{dS}{dt} = \frac{h_s(W_a - W_{fs})}{\rho_f + S_f \left(147.55 e^{0.227 (T_{fs})}\right)}$$

(22)

Here $h_s$ and $i_s$ are the enthalpies of the moist air evaluated at the air temperature and at the frost surface temperature, respectively. Eqs. (21) and (22) are integrated via a standard forward-Euler scheme to find frost thickness $S_f$ and frost surface temperature $T_{fs}$.

The model permits frost to be deposited onto the cave walls and ceiling if those surfaces become sufficiently cold (e.g. colder than the modeled ice plate). If the walls gain frost, then the mass and energy exchange is computed between the wall frost and the cave atmosphere as well via Eq. (14).

The atmospheric model used to drive the ambient air temperature, wind, humidity and air pressure for the Mars ice cave model was the Ames Mars General Circulation Model (MGCM) version 2.1 (Haberle et al., 1999; Nelli et al., 2009). The MGCM data covered 35 $\times$ 60 gridboxes (each gridbox approximately $5^\circ \times 6^\circ$). The area poleward of 87.5$^\circ$ was not included in our model due to MGCM data restrictions. Omitting the extremely high-latitude region is of no concern for this study since those areas are presumed to be covered by residual ice caps, and since we are primarily interested in the lower latitudes. The martian surface layer portion of the output was used to drive the cave model. The Ames MGCM output does, on occasion, permit supersaturation in the boundary layer to occur, however during those times we elected to limit the GCM relative humidities to 100%.

The temporal output resolution of the MGCM data was 1.5 h (90 min), however, we used a substepping resolution of 9 min, primarily to capture cave air temperature changes. The output resolution of the cave model was 9 min. Every 9 min the model would compare air temperatures within and outside of the cave and determine whether air circulation was warranted between the cave and the outside air. If an exchange was required, the air exchange was done instantaneously.

The cave model was applied to the entire martian surface (each of the 35 $\times$ 60 gridboxes) for one martian year. For each gridpoint, the cave wall temperature was first “equilibrated” by running an abbreviated model for one Mars year, and then the actual model was run for that gridbox for one Mars year. The equilibration spin-up was used primarily to determine the approximate cave wall temperature, since it was assumed that it could vary according to the ambient air temperature of the cave air. Once the gridpoint was equilibrated for one simulated year, the full model involving mass and energy balance of the ice, cave air walls, and possible wall ice was run for the gridpoint over an additional Mars year. If the net difference of total ice within the cave (i.e. frost on walls, if any + ice plate) was positive (or zero), indicating a balance or net gain, then we claim that the simulated ice deposit was stable at that location.

3. Model results

As stated previously, the model was run for all gridpoints on the surface of Mars, for a single Mars year (in addition to the 1-year “spinup” period which was used to initialize the cave wall temperature). The GCM run itself was considered to be already equilibrated. The net loss rates of the total ice from the cave after 1 year were computed. The model results are shown in Figs. 3–10. If the amount of ice after 1 year was equal to or exceeded the initial amount, then the gridpoint was considered to be an area where stable cave ice could exist. The numerical experiments do not address the (small-scale) varying geology, and whether caves were possible in special geological environments (discussed below).
Air exchanges between cave air and the outside air typically occur when the outside air temperature is coldest (just prior to sunrise). Fig. 4 shows the diurnal temperature variations of the exterior air, cave air and cave wall skin at an equatorial location. Air exchanges occur during the early morning, at which time the outside air is slightly colder than the cave air. During the daytime, the air in the cave, the cave walls, and the ice warm slightly due to the surrounding cave wall material. During most of the day atmospheric air cannot enter the cave because it is not dense enough, a phenomenon also observed by Wynne et al. (2008) for the non-ice caves of the Atacama desert on Earth.

The base-case results, shown in Fig. 5, indicate that there is a noticeable absence of stable cave ice in the polar regions. The lack of polar cave ice appears to be a seasonal effect. The caves are flushed with new air at night every day throughout the year at lower latitudes. However in the polar regions the air exchanges occur during winter when cold air can sink into the cave. At that time, the polar atmosphere is expected to have tiny quantities of water vapor present. Hence the caves in the polar regions are starved of humid air. The lack of humid air yields only low and sporadic deposition within polar caves. It is expected, however, that annual precipitation at high latitudes would potentially contribute ice in the form of snow. We do not, however, include wind-blown or other forms of precipitation in this particular model.

On the other hand, cave ice would be stable for large portions of the martian surface. In particular, the major volcanic province of Mars, the Tharsis rise (Carr, 1974; Carr and Head, 2009), is among the most favorable regions, with numerous localized very favorable areas in the specific volcanic terrains in which lava channels, tubes (Leveille and Datta, 2010), and skylights (Cushing et al., 2007a,b) have been observed (Fig. 11). Furthermore, the second largest volcanic province on Mars, the Elysium rise is also a favorable location (Fig. 5). Understanding ice cave formation in the lower latitudes is slightly more complicated than understanding the lack of ice cave formation at high latitude. Low-latitudes have relatively high mean annual outside air temperature (Fig. 6) and mean annual ground temperature (Fig. 7), which permit larger amounts of atmospheric water. Lower latitude caves also experience large diurnal temperature variations in the outside air, which lead to frequent nocturnal air exchanges providing a water source for the cave. While the large diurnal temperature variation at lower latitudes can drive moist cold air into the caves at night, there is a zonal asymmetry to cave ice stability. The asymmetry is influenced largely by longitudinal variations in thermal inertia. In the mid-latitudes and tropics, the Tharsis region tends to favor stable cave ice (Fig. 5). For a given (low) latitude the Tharsis region has approximately the same daytime high-temperatures as Margaritifer Terra (approximately 0°N by 30°W). However, the nighttime lows can be 30 K colder on Tharsis than at lower elevations. The effect appears to be mostly due to the lower thermal inertia in the Tharsis area (compared with the Margaritifer Terra region, for example). We stress, however, that the model was somewhat sensitive to values of thermal inertia used (explained below).

4. Model sensitivity tests

Several model parameters were varied in an effort to determine model sensitivities. The frost deposition parameters, GCM water...
amounts and temperatures, ice drag coefficient, the emissivity of the cave walls and the wind speed over the ice plate were varied within a small range and the results are summarized in Table 1. It is interesting to note that none of the sensitivity parameters had extremely large model effects. The largest model sensitivities were due to the GCM-supplied air temperatures and thermal inertia values.

As stated previously we also modeled scenarios where the ground was composed of uniformly high thermal inertia (e.g. rock) and low thermal inertia (e.g. dust) material. Following the values used in Putzig and Mellon (2007), high thermal inertia material was taken to be rock with a density of 2500 kg/m³, thermal inertia of 2506 TIU, $C_p$ of 837 J/kg K and an inferred thermal conductivity of 3.0012 W/mK. The low thermal inertia case assumed a dust material with a density of 1375 kg/m³, thermal inertia of 56 TIU, $C_p$ of 837 J/kg K and an inferred thermal conductivity of 0.0027 W/mK. The results of these additional sensitivity tests are shown in Figs. 9 and 10.

It is also interesting to note from Fig. 10 that higher thermal conductivity of the cave walls appears to provide a natural negative feedback to overall cave ice deposition. The GCM temperatures were not changed for the runs of Figs. 9 and 10; only the wall thermal inertia (and hence thermal conductivity) was changed. The high thermal inertia serves to diminish the influence of cold cave air on the wall temperatures. Low thermal inertia of the cave walls permits the cold cave air to chill the walls, creating a cave environment more conducive to ice formation. Note that the cave walls are not responding to thermal energy propagating through the ground into the cave. Rather as shown in Fig. 4 the walls are responding to the temperature of the air entering the cave.
5. Discussion and conclusion

The base-case results (Fig. 5) and our model sensitivity tests indicate that cave ice would be stable for significant portions of Mars. From a geological standpoint, it is well-known from terrestrial studies that ice caves are common occurrences in lava tubes in various volcanic terrains and environments. Knutson (1972) described three major lava tube systems in Oregon: these extend from 2 to almost 14 km in length, are as deep as 40 m below the surface, have roof sections up to 25 m thick, and often have collapsed segments and skylights. Lava caves are common in volcanic terrains in the western part of North America (Knutson, 1969, 1970; Greeley, 1971; Greeley and Hyde, 1972); many ice cave segments are well-known and the mechanisms for ice development have been studied (e.g., Macdonald, 1993).

Mars has been significantly resurfaced by volcanic activity in the course of its lifetime (Carr, 1973). In addition to major areas of the planet resurfaced by volcanic flows in the Hesperian period (Greeley and Spudis, 1981; Carr and Head, 2009), the two major
estimates the deposition in the low-wind case since the Sherif et al. in the cave, however our frost deposition scheme probably under estimating to our airflow model we do have low-speed winds at all times wind speeds somewhat higher than the winds in the cave. Accord a formulation designed for a forced (wind-driven) situation with areas where cave ice is stable on Mars.

Given this approach, there are substantial areas in the present-day Martian tropics where cave ice deposits (while they slowly sublimate) would survive for long periods. Thicker ice deposits in caves, while not specifically modeled in this paper, may last much longer (e.g. 100,000 years).

If such ice deposits were to survive for timescales of 100,000 years, they could be remnants of an obliquity maximum (of up to 35°) which is hypothesized to have occurred over this timescale (Laskar, 2004) and deposited ice at mid-latitudes that is currently thought to be preserved under a cover of sublimation lag (Head et al., 2006, 2010). Mischna et al. (2003) have found that under high obliquities (35° and higher) there could have been centimeters of ice seasonally deposited at low-latitudes and hundreds of meters to kilometers over longer time periods at mid-latitudes (Madeleine et al., 2009). Holt et al. (2008) and Plaut et al. (2009) have shown evidence from SHARAD radar data of large amounts of buried ice in the present-day mid-latitudes of Mars in many of the locations described by Head et al. (2006, 2010). In addition, volcanic provinces of Mars, the Tharsis and Elysium rises, are also characterized by numerous channels and collapsed lava tubes (Fig. 11). Our analysis thus shows that areas suspected of having subsurface caves and related voids on the basis of the geologic evidence, are also among the most favorable regions for the occurrence of ice stability in such caves (Fig. 5).

It should be noted that our frost deposition scheme is based on a formulation designed for a forced (wind-driven) situation with wind speeds somewhat higher than the winds in the cave. According to our airflow model we do have low-speed winds at all times in the cave, however our frost deposition scheme probably underestimates the deposition in the low-wind case since the Sherif et al. (1993) equations predict no frost deposition whatsoever in the zero-wind case. Hence we believe our frost deposition and cave ice stability estimates to be conservative; there may be additional areas where cave ice is stable on Mars.

An interesting way to interpret the inferred loss rates in Fig. 5 is to consider the lifetime of previously deposited ice. For example, given a loss rate of 0.029 kg/year, a cave containing a 1 m – thick ice plate on the cave floor would presumably last ~34,000 years. Given this approach, there are substantial areas in the present-day Martian tropics where cave ice deposits (while they slowly sublimate) would survive for long periods. Thicker ice deposits in caves, while not specifically modeled in this paper, may last much longer (e.g. 100,000 years).

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In this study we have neglected the possibility of dust layers on top of the cave ice deposits. The effects of an overlying dust layer on cave ice are unknown. Some work has been done previously on the effect of a dust top layer in snowpacks exposed to sunlight on Mars (Williams et al., 2008), however the effect of such a layer, when there is no sunlight, is unclear. It is possible that the effect would be minimal for the mass transfer between the ice surface and the atmosphere as long as the water vapor permeability is high.

Additional research is necessary in order to determine whether the frost deposition model of Sherif et al. (1993) is indeed an effective predictor of frost deposition in a low-pressure (and low-temperature) CO2 atmosphere. Nevertheless, given the lack of sensitivity in the model to the frost deposition scheme (the first two density parameters listed in Table 1), it is likely that the deposition model is adequate.

The results in this study suggest that there are extensive areas where ice may be preserved for long timescales in Martian cave environments. The possibility that ice may be preserved in Martian caves and/or karst terrain is of astrobiological importance, as well as of importance to any potential human exploration missions to Mars.

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Appendix A. Lattice-Boltzmann Models

The airflow pattern within the cave has been simulated in this study with a 2-D computational fluid dynamics (CFD) model known as a Lattice-Boltzmann Model (LBM). Such models have been previously applied to airflow situations with good success (Masselot and Chopard, 1998; Jimenez-Hornero et al., 2005). LBMs have several advantages over traditional finite-difference methods, not the least of which is that LBMs are much better suited to modeling complex geometries, in this case a cave with a chimney. LBMs are a modern variant of the lattice-gas automata (LGA) model of Frisch et al. (1986), where it was shown that lattice gases modeled with discrete elements were capable of simulating the Navier–Stokes equations. Building on successes of the LGA models, LBMs have become a popular choice for simulating the Navier–Stokes equations, especially in the incompressible limit (Yu, 2003; Hou et al., 1995, among others).
Unlike the traditional methods of solving the Navier–Stokes equations, LBMs instead solve the kinetic equation. The particle velocity distribution function $f(x, v, t)$ on a lattice, where $x$ is the position vector, $v$ is the particle velocity vector, and $t$ is time. The macroscopic quantities of momentum density and mass density are recovered by evaluating moments of $f$. In general, the LBM is a Lagrangian solution on a lattice to the continuum kinetic equation

$$\frac{\partial f}{\partial t} + \mathbf{e}_x \cdot \nabla f = \Omega_x$$

(A1)

where $\Omega_x$ is the so-called collision operator and $\mathbf{e}_x$ the velocity vectors in directions $x = 0, \ldots, 8$ for a square lattice.

Our particular kinetic model used to simulate cave airflow in our model is a two-dimensional form of the Bhatnagar–Gross–Krook (BGK) collision model,

$$\frac{\partial f}{\partial t} + \mathbf{e}_x \cdot \nabla f = -\frac{1}{\tilde{c}} (f_x - f_x^0)$$

(A2)

where a single relaxation time $\tilde{c}$ is used to approximate the collision integral, and $f_x^0$ denotes the equilibrium distribution function. Using the same notation as Yu (2003) for the two-dimensional nine-velocity (D2Q9) model, the particle (microscopic) velocities are computed via

$$e_0 = 0$$

$$e_x = \frac{\tilde{c}}{2} \cos \left( (x - 1) \frac{\pi}{4} \right), \sin \left( (x - 1) \frac{\pi}{4} \right)$$

for $x = 1, 3, 5, 7$

$$e_x = \sqrt{2} \tilde{c} \cos \left( (x - 1) \frac{\pi}{4} \right), \sin \left( (x - 1) \frac{\pi}{4} \right)$$

for $x = 2, 4, 6, 8$ (A3)

where the lattice speed $c = \frac{\tilde{c}}{\sqrt{2}}$ is the lattice spacing and $\tilde{c}$ is the time interval. The equilibrium state is given by:

$$f_x^0 = \rho w_x \left( 1 + \frac{3}{c^2} e_x^2 + \frac{9}{2c^4} (e_x^2 u^2 - \frac{3}{2c^2} u^2) \right)$$

(A4)

where the vector $u$ is the macroscopic velocity and the weights are given by

$$w_x = \frac{4}{9}$$

for $x = 0$

$$w_x = \frac{1}{9}$$

for $x = 1, 3, 5, 7$

$$w_x = \frac{1}{36}$$

for $x = 2, 4, 6, 8$ (A5)

On the lattice, density and momentum are computed via

$$\rho = \sum_{x=0}^{8} f_x$$

(A6)

$$\rho u = \sum_{x=0}^{8} e_x f_x$$

(A7)

The evolution of the particle distribution function $f$ on a lattice and for direction $x$ can be written as

$$f_x(x + e_x \delta t, t + \delta t) - f_x(x, t) = -\frac{1}{\tilde{c}} (f_x(x, t) - f_x^0(x, t))$$

(A8)

where $\tau$ is a relaxation parameter. Following the work of Hou et al. (1994) we have modified the collision step to allow for higher Reynolds numbers (~103) by adjusting the relaxation time according to local velocity gradients (i.e. by applying a Smagorinsky subgrid scale modification to $\tau$).

The model is then evaluated by the "collide and stream approach" by first executing a collision step for a given lattice point, followed by a streaming step (where $f$ is propagated to neighboring lattice points). We have validated a somewhat simplified lid-driven cavity form of the above model (as have others) by comparing the velocity transsects at the geometric center of the cavity with the numerical results of Ghia et al. (1982).